

TANDEM POWERED POWER TILTING AIRCRAFT

TECHNICAL FIELD

This invention relates to the vertical take-off field of aviation.

5 BACKGROUND ART

Many versions of helicopters using tandem rotors have been constructed to date. What has been common to all such helicopters is that the lifting rotors have had to have variable pitch blades to allow control of the helicopters.

10 SUMMARY OF THE INVENTION

This invention provides an aircraft that can fly in a similar manner to a conventional tandem rotor helicopter but does not require a blade pitch varying mechanism.

15 DETAILED DESCRIPTION OF THE INVENTION

The aircraft has a main body that is longer than it is wider, a lifting mechanism at the front, which is the primary lifting mechanism, and another lifting mechanism at the rear, which is a secondary lifting mechanism.

20 The primary lifting mechanism is joined to the forward part of the main body of the aircraft by a tilt enabling joint, and the secondary lifting mechanism is joined to the aft part of the main body of the aircraft by another tilt enabling joint.

The tilt enabling joints provide the means to position the lifting mechanisms above the main body of the aircraft and the means to tilt the primary and secondary lifting mechanisms in a plurality of directions and angles in a controlled 5 manner relative to the main body of the aircraft. Referring to the tilt enabling joint that can tilt the primary lifting mechanism as a primary tilt enabling joint, the primary lifting mechanism can be tilted forward, rearward, and from side to side with respect to the main body of the aircraft by 10 means of the primary tilt enabling joint. And referring to the tilt enabling joint that can tilt the secondary lifting mechanism as a secondary tilt enabling joint, the secondary lifting mechanism can be tilted forward, rearward, and from side to side with respect to the main body of the aircraft 15 by means of the secondary tilt enabling joint.

Tilting of the lifting mechanisms is used as a means to control the aircraft instead of varying blade pitches. By using tilting of lifting mechanisms to control the aircraft during flight, combinations of different forms of 20 lifting mechanisms can be used. For example, the front lifting mechanism can be in the form of a rotor with fixed pitch blades and an engine assembly, with the blades able to force air in a downward direction, while the rear lifting mechanism can be a jet engine which can force exhaust gases

directly downward or downward and sideways, depending on the
tilting of the jet. By being able to tilt the jet forward
and rearward, and from side to side, changes in exhaust
direction can be achieved. Sideway directed exhaust can be
5 used to counter the torque of the forward rotor during take
off. Because the aircraft has a jet at the rear instead of
a rotor, the downwash over the rear part of the body of the
aircraft from rotor blades is avoided. As such wings can be
fitted to the rear of the aircraft. On conventional
10 helicopters wings have been proven to be useless due to
downwash from rotor blades. With wings fitted to the current
invention, the aircraft could gain substantial lift during
high speed forward flight, reducing the need to rely on the
jet at the rear for lift. By fitting the forward lifting
15 rotor and engine to the main body of the aircraft with
multiple tilt enabling joints, the forward lifting mechanism
could be tilted 90 degrees forward during forward flight,
thus overcoming the need for a counter torque mechanism
during high speed forward flight. The jet can then be tilted
20 into a horizontal position, adding to forward propulsion.
The aircraft in effect can be transformed into a high speed
forward flying aeroplane, using a massive sized rotor at
the front acting as a propeller on an aeroplane and a jet
at the rear for forward propulsion. The wings would provide

lift, and ailerons on the wings could counter the torque from the main rotor during high speed forward flight.

With the primary lifting mechanism at the front of the aircraft comprising a rotor with a plurality of blades connected to the 5 rotor, and the rotor being rotated by an engine assembly to force air to travel in a downward direction, the engine assembly can consist of a single engine or a plurality of engines.

Since the rotor blades don't have to be varied as in a 10 conventional helicopter, a simple option could be to use a turboprop as the primary lifting mechanism, positioned on the primary tilt enabling joint such that during take-off air is forced in a downward direction by means of the blades that form part of the turboprop.

15 While the secondary lifting mechanism can in one form be a jet engine, it can in another form be a rotor with a plurality of blades connected to the rotor, with an engine assembly to rotate the rotor, and by rotation of the rotor force air in a downward direction by means of the blades as the blades travel 20 around the rotor. The engine assembly can be a single engine or a plurality of engines. In another form the secondary lifting mechanism can be a turboprop.

Hence it becomes apparent that different types of lifting mechanisms can be combined on the aircraft.

In one form of the aircraft the primary lifting mechanism comprises an engine assembly, a rotor, and blades connected 5 to the rotor, with the engine assembly able to rotate the rotor and the blades connected to the rotor such that air can be forced to travel in a downward direction by means of the blades rotating around the rotor, while the secondary lifting mechanism also comprises an engine 10 assembly, a rotor, and blades connected to the rotor, with the engine assembly of the secondary lifting mechanism able to rotate the rotor of the secondary lifting mechanism and the blades of the secondary lifting mechanism connected to the rotor of the secondary lifting 15 mechanism such that air can be forced to travel in a downward direction by means of the blades of the secondary lifting mechanism rotating around the rotor of the secondary lifting mechanism.

In another form of the aircraft the primary lifting 20 mechanism is a turboprop which is positioned on the primary tilt enabling joint such that air can be forced in a downward direction by means of the blades of the turboprop, and the secondary lifting mechanism is a

turboprop, which is positioned on the secondary tilt enabling joint such that air can be forced in a downward direction by means of the blades of the turboprop.

In another form of the aircraft the primary lifting
5 mechanism comprises an engine assembly, a rotor, and
blades connected to the rotor, with the engine assembly
able to rotate the rotor and the blades connected to
the rotor such that air can be forced to travel in a
downward direction by means of the blades rotating
10 around the rotor, and the secondary lifting mechanism
is a turboprop which is positioned on the secondary
tilt enabling joint such that air can be forced in a
downward direction by means of the blades of the
turboprop.

15 In another form of the aircraft the primary lifting
mechanism is a turboprop which is positioned on the
primary tilt enabling joint such that air can be forced in a
downward direction by means of the blades of the turboprop,
while the secondary lifting mechanism comprises an
20 engine assembly, a rotor, and blades connected to the
rotor, with the engine assembly of the secondary lifting
mechanism able to rotate the rotor of the secondary lifting
mechanism and the blades of the secondary lifting mechanism
connected to the rotor of the secondary lifting mechanism

such that air can be forced to travel in a downward direction by means of the blades of the secondary lifting mechanism rotating around the rotor of the secondary lifting mechanism.

- 5 In another form of the aircraft the primary lifting mechanism comprises an engine assembly, a rotor, and blades connected to the rotor, with the engine assembly able to rotate the rotor and the blades connected to the rotor such that air can be forced to travel in a downward direction by means of the blades rotating around the rotor, and the secondary lifting mechanism is a jet engine in the form of a turbojet that can be tilted so that exhaust from the turbojet can be forced in a downward direction behind the main body of the aircraft.
- 10 In another form of the aircraft the primary lifting mechanism comprises an engine assembly, a rotor, and blades connected to the rotor, with the engine assembly able to rotate the rotor and the blades connected to the rotor such that air can be forced to travel in a downward direction by means of the blades rotating around the rotor, and the secondary lifting mechanism is a jet engine in the form of a turbojet that can be tilted so that exhaust from the turbojet can be forced in a downward direction behind the main body of the aircraft.
- 15 In another form of the aircraft the primary lifting mechanism comprises an engine assembly, a rotor, and blades connected to the rotor, with the engine assembly able to rotate the rotor and the blades connected to the rotor such that air can be forced to travel in a downward direction by means of the blades rotating around the rotor, and the secondary lifting mechanism is a jet engine in the form of a turbojet that can be tilted so that exhaust from the turbojet can be forced in a downward direction behind the main body of the aircraft.
- 20 In another form of the aircraft the primary lifting mechanism comprises an engine assembly, a rotor, and blades connected to the rotor, with the engine assembly able to rotate the rotor and the blades connected to the rotor such that air can be forced to travel in a downward direction by means of the blades rotating around the rotor, and the secondary lifting mechanism is a jet engine in the form of a turbojet that can be tilted so that exhaust from the turbojet can be forced in a downward direction behind the main body of the aircraft.

In another form of the aircraft the primary lifting mechanism is a turboprop which is positioned on the primary tilt enabling joint such that air can be forced in a downward direction by means of the blades of the 5 turboprop, and the secondary lifting mechanism is a jet engine in the form of a turbojet that can be tilted so that exhaust from the turbojet can be forced in a downward direction behind the main body of the aircraft.

In another form of the aircraft the primary lifting 10 mechanism is a turboprop which is positioned on the primary tilt enabling joint such that air can be forced in a downward direction by means of the blades of the turboprop, and the secondary lifting mechanism is a jet engine in the form of a turbofan that can be tilted so 15 that exhaust from the turbofan can be forced in a downward direction behind the main body of the aircraft.

In another form of the aircraft the primary lifting mechanism comprises an engine assembly, a rotor, and blades connected to the rotor, with the engine assembly 20 able to rotate the rotor and the blades connected to the rotor such that air can be forced to travel in a downward direction by means of the blades rotating around the rotor, and the secondary lifting mechanism comprises two jet engines that can be tilted so that exhaust from the

jet engines can be forced in a downward direction behind the main body of the aircraft, with each jet engine being a turbojet.

In another form of the aircraft the primary lifting mechanism comprises an engine assembly, a rotor, and 5 blades connected to the rotor, with the engine assembly able to rotate the rotor and the blades connected to the rotor such that air can be forced to travel in a downward direction by means of the blades rotating around the rotor, and the secondary lifting mechanism 10 comprises two jet engines that can be tilted so that exhaust from the jet engines can be forced in a downward direction behind the main body of the aircraft, with each jet engine being a turbofan.

In another form of the aircraft the primary lifting 15 mechanism is a turboprop which is positioned on the primary tilt enabling joint such that air can be forced in a downward direction by means of the blades of the turboprop, and the secondary lifting mechanism comprises two jet engines that can be tilted so that exhaust 20 from the jet engines can be forced in a downward direction behind the main body of the aircraft, with each jet engine being a turbofan.

In another form of the aircraft the primary lifting mechanism is a turboprop which is positioned on the 25 primary tilt enabling joint such that air can be forced

in a downward direction by means of the blades of the turboprop, and the secondary lifting mechanism comprises two jet engines that can be tilted so that exhaust from the jet engines can be forced in a downward direction behind the main body of the aircraft, with each jet engine being a turbofan.

In one form of the aircraft where the primary lifting mechanism comprises an engine assembly, a rotor, and blades connected to the rotor, with the engine assembly 10 able to rotate the rotor and the blades connected to the rotor such that air can be forced to travel in a downward direction by means of the blades rotating around the rotor, the engine assembly consists of a single engine.

In another form of the aircraft where the primary lifting 15 mechanism comprises an engine assembly, a rotor, and blades connected to the rotor, with the engine assembly able to rotate the rotor and the blades connected to the rotor such that air can be forced to travel in a downward direction by means of the blades rotating around the 20 rotor, the engine assembly consists of two engines.

In one form of the aircraft where the primary lifting mechanism comprises an engine assembly, a rotor, and blades connected to the rotor, and the engine assembly of

the primary lifting mechanism consists of a single engine, a power transmission mechanism is connected to the engine of the primary lifting mechanism, by which power transmission mechanism the respective engine is able to
5 rotate the rotor of the primary lifting mechanism.

In another form of the aircraft where the primary lifting mechanism comprises an engine assembly, a rotor, and blades connected to the rotor, and the engine assembly of the primary lifting mechanism consists of two engines,
10 a power transmission mechanism is connected to the engines of the primary lifting mechanism, by which power transmission mechanism the engines of the primary lifting mechanism are able to rotate the rotor of the primary lifting mechanism.

In one form of the aircraft where the secondary lifting mechanism comprises an engine assembly, a rotor, and blades connected to the rotor of the secondary lifting mechanism, the engine assembly of the secondary lifting mechanism consists of a single engine.

In another form of the aircraft where the secondary lifting mechanism comprises an engine assembly, a rotor, and blades connected to the rotor of the secondary lifting mechanism, the engine assembly consists of two engines.

In one form of the aircraft where the secondary lifting mechanism comprises an engine assembly, a rotor, and

blades connected to the rotor of the secondary lifting mechanism, and the engine assembly consists of a single engine, a power transmission mechanism is connected to the engine of the secondary lifting mechanism, by which power 5 transmission mechanism the respective engine is able to rotate the rotor of the secondary lifting mechanism.

In another form of the aircraft where the secondary lifting mechanism comprises an engine assembly, a rotor, and blades connected to the rotor, and the engine assembly 10 of the secondary lifting mechanism consists of two engines, a power transmission mechanism is connected to the engines of the secondary lifting mechanism by which power transmission mechanism the engines of the secondary lifting mechanism are able to rotate the rotor of the secondary lifting mechanism.

15 The tilt enabling joints can comprise various components. Some of the components are such that they hold the joint together while allowing the joint to have movement, forming a movement enabling assembly, while other components form an activating mechanism that can force movement between 20 components of the movement enabling assembly.

In one form of the aircraft the movement enabling assembly of the primary tilt enabling joint is a universal joint and the activating mechanism comprises four of hydraulic actuators connected to the movement enabling assembly.

In another form of the aircraft the movement enabling assembly of the primary tilt enabling joint comprises a hinge assembly and the activating mechanism comprises a hydraulic actuating mechanism connected to the movement
5 enabling assembly.

In another form of the aircraft the movement enabling assembly of the primary tilt enabling joint comprises two hinges transversely connected and the activating mechanism comprises four hydraulic
10 actuators connected to the movement enabling assembly.

In one form of the aircraft the movement enabling assembly of the secondary tilt enabling joint is a universal joint and the activating mechanism comprises four hydraulic actuators connected to the movement
15 enabling assembly.

In another form of the aircraft the movement enabling assembly of the secondary tilt enabling joint comprises a hinge assembly and the activating mechanism comprises a hydraulic actuating mechanism connected to the movement
20 enabling assembly.

In another form of the aircraft the movement enabling assembly of the secondary tilt enabling joint comprises two hinges transversely connected and the activating mechanism comprises four hydraulic
25 actuators connected to the movement enabling assembly.

In one form of the aircraft the primary lifting mechanism is connected to the main body of the aircraft by the primary tilt enabling joint such that only part of the primary lifting mechanism can be positioned in front of the main body of the aircraft.

In another form of the aircraft the primary lifting mechanism is connected to the main body of the aircraft by the primary tilt enabling joint such that the whole of the primary lifting mechanism can be positioned in front of the main body of the aircraft.

In one form of the aircraft the primary lifting mechanism is connected to the main body of the aircraft by the primary tilt enabling joint such that only a part of the primary lifting mechanism can be positioned above the main body of the aircraft.

In another form of the aircraft the primary lifting mechanism is connected to the main body of the aircraft by the primary tilt enabling joint such that the whole of the primary lifting mechanism can be positioned above the main body of the aircraft.

In one form of the aircraft the secondary lifting mechanism is connected to the main body of the aircraft by the secondary tilt enabling joint such that only part of the secondary lifting mechanism can be positioned behind the main body of the aircraft.

In another form of the aircraft the secondary lifting mechanism is connected to the main body of the aircraft by the secondary tilt enabling joint such that the whole of the secondary lifting mechanism can be positioned behind the 5 main body of the aircraft.

In one form of the aircraft the secondary lifting mechanism is connected to the main body of the aircraft by the secondary tilt enabling joint such that only part of the secondary lifting mechanism can be positioned above 10 the main body of the aircraft.

In another form of the aircraft the secondary lifting mechanism is connected to the main body of the aircraft by the secondary tilt enabling joint such that the whole of the secondary lifting mechanism can be positioned above 15 the main body of the aircraft.

In another form of the aircraft an additional tilt enabling joint is used to connect the primary tilt enabling joint to the main body of the aircraft to allow a greater amount of tilting movement between 20 the primary lifting mechanism and the main body of the aircraft. The additional tilt enabling joint, which is a third tilt enabling joint, comprises a movement enabling assembly that is a hinge, and the

activating mechanism comprises two hydraulic actuators connected to the movement enabling assembly and the main body of the aircraft.

In one form of the aircraft the secondary lifting mechanism is pivotally connected to the secondary tilt enabling joint such that the secondary lifting mechanism can be rotated on the secondary tilt enabling joint without the secondary tilt enabling joint having to move. In a form of the aircraft this rotating ability is achieved 10 by means of a metal plate being used to join the secondary lifting mechanism to the upper section of the secondary tilt enabling joint, with the metal plate being joined to the upper section of the secondary tilt enabling joint by means of a large rivet, and an electric 15 motor that turns a wheel is used to rotate the metal plate on the secondary tilt enabling joint, with the electric motor connected to the secondary tilt enabling joint and the wheel.

In another form of the aircraft the secondary tilt enabling joint is connected to the main body of the aircraft such that the secondary tilt enabling joint can be rotated on the aft end of the main body of the aircraft without components of the secondary tilt enabling joint having to move with respect to one another. In a form of the aircraft this rotating 20

ability is achieved by means of a metal plate being used to join the lower section of the secondary tilt enabling joint to the upper part of the aft end of the main body of the aircraft, with the metal plate being joined to 5 the upper part of the main body by means of a large rivet which protrudes from inside of the main body of the aircraft. An electric motor that turns a wheel is used to rotate the metal plate that the secondary tilt enabling joint is attached to, with the electric motor 10 connected to the upper section of the main body of the aircraft.

Figure 1 shows one form of the aircraft according to this invention. The aircraft has a main body 1 with a forward end 2 and an aft end 3. The primary 15 lifting mechanism 4 comprises two blades 5, 6, connected to a rotor 7, which rotor 7 is rotated by means of an engine assembly 8 comprising one engine. The primary lifting mechanism 4 is connected to the top of the forward end 2 of the main body 1 by 20 means of the primary tilt enabling joint 9 which has a movement enabling assembly in the form of a universal joint 10. A hydraulic actuator 11 is able to move the upper section 12 of the primary tilt enabling joint 9 forward and the hydraulic

actuator 13 is able to move the upper section 12 of the primary tilt enabling joint in a rearward direction, while another hydraulic actuator 14 is connected to the main body 1 of the aircraft so that it is on the left side of the universal joint 10 and so that it is able to tilt a metal platform 15 which forms part of the universal joint 10 to the right side of the main body (Refer Figure 2). Another hydraulic actuator 16 is connected 5 to the main body 1 of the aircraft so that it is on the right side of the universal joint and so that it can tilt the metal platform 15 to the left side of the main body of the aircraft. The hydraulic actuator 14 is positioned behind the 10 universal joint 10 but is further forward on the main body than is the hydraulic actuator 16. The hydraulic actuators 14 and 16 are connected to the main body 1 and the metal platform 15 that forms part of the universal 15 joint 10. The hydraulic actuators 11 and 13 are 20

connected to the metal platform 15 and the upper section 12 of the primary tilt enabling joint 9. The secondary lifting mechanism 17 comprises a blades 18, 19, connected to a rotor 20, which rotor 20 is rotated by means of an engine assembly 21 that comprises a single engine. The secondary lifting mechanism 17 is connected to the top of the aft end 3 of the main body 1 by means of the secondary tilt enabling joint 22 which has a movement enabling assembly in 10 the form of a universal joint 23. A hydraulic actuator 24 is able to move the upper section 25 of the secondary tilt enabling joint 22 rearward with respect to the main body 1 and the hydraulic actuator 26 is able to move the upper section 25 15 of the secondary tilt enabling joint in a forward direction, while another hydraulic actuator 27 is connected to the main body 1 of the aircraft so that it is on the left side of the universal joint 23 and so that it is able to tilt a metal platform

28 which forms part of the universal joint 23 to the right side of the main body. Another hydraulic actuator 29 is connected to the main body 1 of the aircraft so that it is on the right side of the 5 universal joint 23 so that it can tilt the metal platform 28 to the left side of the main body of the aircraft. The hydraulic actuator 27 is positioned further forward on the main body than is the hydraulic actuator 29. The hydraulic actuators 27 and 29 are 10 connected to the main body 1 and the metal platform 28 that forms part of the universal joint 23. The hydraulic actuators 24 and 26 are connected to the metal platform 28 and the upper section 25 of the secondary tilt enabling joint 15 22. The universal joint 10 of the primary tilt enabling joint 9 is formed by transversely connecting hinges 30 and 31 by means of the metal platform 15. The universal joint 23 of the secondary tilt enabling joint 22 is formed by 20 transversely connecting hinges 32 and 33 by means of the metal platform 28. The hinges 30 and 32 are joined

to the upper part of main body 1 of the aircraft. By forcing air in a downward direction by means of the primary lifting mechanism and the secondary lifting mechanism the aircraft is able to achieve vertical take-off.

5 By tilting the primary lifting mechanism forward by means of the primary tilt enabling joint and tilting the secondary lifting mechanism forward by means of the secondary tilt enabling joint the aircraft is able to achieve forward flight

10 as air is force downward and to the rear of the aircraft by the primary lifting mechanism and secondary lifting mechanism. The primary lifting mechanism and the secondary lifting mechanism are arranged in tandem order above the main body 1,

15 with primary lifting mechanism forward of the secondary lifting mechanism. The primary tilt enabling joint and the secondary tilt enabling joint are also in tandem order on top of the main body 1, with the primary tilt enabling joint in

20 front of the secondary tilt enabling joint. The

blades of the primary lifting mechanism protrude in front of the forward end of the main body 1.

Figure 2 shows the lower part of the primary tilt enabling joint 9 at the forward end of the main body 1 of the aircraft of Figure 1. The view is from behind and shows the universal joint 10 as it would appear from behind, and the positioning of hydraulic actuators 14 and 16, with hydraulic actuator 14 to the left of the universal joint 10 and hydraulic actuator 16 to the right of the universal joint 10. The hydraulic actuators are connected to the metal plate 15 that forms part of the universal joint.

The hydraulic actuators 27 and 29 of the secondary tilt enabling joint 22 of Figure 1 are distanced in the same manner from the universal joint 23 as the hydraulic actuators 14 and 16 are distanced from the universal joint 10 of the primary tilt enabling joint.

Figure 3 shows another form of the aircraft. The aircraft has a main body 1 as in figure 1, with a forward end 2 and an aft end 3. The primary tilt enabling joint 9 is the same as in Figure 1 and the secondary tilt enabling joint 22 is the same as in Figure 1. The primary lifting mechanism 4 is a turboprop 34 which can force air in a downward direction by means of the blades 35 and 36. The secondary lifting mechanism 17 is another turboprop 10 37 which can force air in a downward direction by means of the blades 38 and 39.

Figure 4 shows another form of the aircraft. The aircraft has a main body 1 with a forward end 2 and rear end 3. The primary lifting mechanism 4 is 15 the same as in Figure 1 and the primary tilt enabling joint 9 is the same as in Figure 1. The secondary lifting mechanism 40 is a jet engine. The jet engine 4 is turbojet and is attached to a hinge 41. The turbojet 40 is joined to metal plate 42 that forms of

the hinge 41. A lower metal plate 43 forms part of the hinge 41. The lower metal plate 43 is connected to another hinge 44 that is positioned longitudinally on top of the main body 1. The lower hinge 44 is joined 5 to the the upper part of the main body 1 of the aircraft.

The hinges 41 and 44 are transversely connected.

A hydraulic actuator 45 is connected to the metal plates 42 and 43 of hinge 41 such that it is able to tilt the turbojet 40 in a rearward direction by pushing 10 the metal plate 42 in a rearward direction. A hydraulic actuator 46 is connected to the lower metal plate 43 and the upper part of the main body and is connected to the main body 1 of the aircraft so that it is on the left of the lower hinge 44 such that it can tilt 15 the lower plate 43 to the right. Another hydraulic actuator 47 is connected to the upper part of the main body and the lower metal plate 43, and is connected to the main body 1 of the aircraft so that it is on the right side of the lower hinge 44 such that it

can tilt the lower plate 43 to the left side of the main body 1. The metal plates 42, 43, the hinges 41 and 44, the and the hydarulic actuators 45, 46, and 47 form the secondary tilt enabling joint 22. The jet 5 engine 40 is shown to be partly behind the main body 1 of the aircraft angled such that it forces exhaust gases in a downward direction through the rear 48 of the turbojet 40. A turbofan jet engine could be used in place of the turbojet 40 positioned in the same manner 10 as the turbojet 40.

Figure 5 shows the front of lower part of the secondary tilt enabling joint 22 of Figure 4 as veiwed from in front of the secondary tilt enabling joint 22. Figure 5 shows the lower hinge 44 connected to the lower plate 43 15 of Figure 4 and the main body 1 of the aircraft, and the distancing of the hydraulic actuators 46 and 47 from the lower hinge 44.

Figure 6 shows the aircraft of Figure 4 fitted with an additional tilt enabling joint 49, which 20 is a third tilt enabling joint. Referring to the

additional tilt enabling joint as a third tilt enabling joint, the third tilt enabling joint 49 is in the form of a hinge 50 which is connected to the upper part of the forward end 2 of the 5 main body 1 of the aircraft. A hydraulic actuator 51 that forms part of the third tilt enabling joint is able to tilt the upper section 52 of the third tilt enabling joint in a forward direction. The primary tilt enabling joint 10 9 is connected to the upper section of the 52 of the third tilt enabling joint and is shown in a state of forward tilt. Hydraulic actuator 53 forms part of the third tilt enabling joint and is able to tilt the upper section 52 of the 15 third tilt enabling joint in a rearward direction. The hydraulic actuator 51 is connectd to a stem 54 protruding from the hing 50 and to the upper part of the main body of the aircraft. The hydraulic actuator 53 is connected to the stem 54

and the upper part of forward end 2 of the main body of the aircraft.

Figure 7 shows a modified form of the aircraft of Figure 6, with the third tilt enabling joint 49 in a forward tilt, the primary tilt enabling joint 9 in a forward tilt, and the jet engine 40 in a forward tilt. Figure 7 shows that the whole of the primary lifting mechanism is in front of the main body of the aircraft. In Figure 7 the aircraft is different 10 to the aircraft in Figure 6 in that it has the lower hinge 44 connected to a metal plate 55. The metal plate 55 is connected to a large rivet 56 which is contained within the main body and protrudes from the main body 1 through an opening 57 in the upper 15 part of the main body. The metal plate 55 is supported on metal blocks 58 and 59 such that the metal plate 55 can be rotated by an electric motor 60 rotating a wheel 61. Hydraulic actuators 46 and 47 are connected to the metal plate 55 and are in the same position

with respect to the hinge 44 as they are in the aircraft of Figure 4. Figure 7 also shows a fin 62 attached to the jet engine 40. The jet is shown further behind the on the aft end of the main body of the 5 aircraft. The jet engine 40 could now be tilted in rearward direction so that it could be placed behind the main body of the aircraft.

Figure 8 shows the aircraft of Figure 7, now fitted with wheel assemblies 63 and 64. Wings can 10 be fitted to the main body of the aircraft. Figure 6 shows the position of a wing 65 on the left side of the main body of the aircraft.

Figure 9 shows a variation of the aircraft of Figure 4. The upper metal plate 42 of the hinge 41 is longer, the 15 jet engine 40 is attached to another metal plate 66, and a large rivet 67 now joins the metal plate 66 to the metal plate 42, which rivet connects the metal plates 42 and 66 such that the metal plate 66 can pivotally rotate with respect to the metal plate 42. A hydraulically

activated rotating arm 68 is used to rotate the metal plate 66 with respect to the metal plate 42. The rivet 67 and the hydraulically activated rotating arm 68 combined with the additional metal plate 66 hence form a rotation

5 enabling mechanism by which the jet engine 40 can be pivotally rotated with respect to the secondary tilt enabling joint.

Figures 1, 3, 4 and 9 show that the aircraft can take off and land vertically. Figure 8 shows that the aircraft can also take off and land as a conventional forward flying

10 aeroplane when fitted with wheels, wings, and when the tilt enabling joints have tilted the primary lifting mechanism and the secondary lifting mechanism forward. The aircraft could take-off while moving forward as an aeroplane and land as a helicopter, and vice versa.

15 Figure 10 shows another form of the aircraft, with the whole of the primary lifting mechanism 4 now in front of and above the forward end 2 of the main body 1. The secondary lifting mechanism 17 is now completely above and behind the aft end of the

20 main body 1. The primary tilt enabling joint 9 and the secondary tilt enabling joint 22 are combinations of components of tilt enabling joints shown in previous figures. An addition is the extension platform 69 shown in respect of the

25 primary tilt enabling joint 9 and the extension platform 70 of the secondary tilt enabling joint 22.

ABSTRACT

An aircraft with a long body 1 which has a forward end 2 and an aft end 3, which is able to achieve vertical take-off by means of a tilttable rotor and 5 blade assembly 4 at the forward part of the aircraft and a tilttable turbojet 40 at the rear of the aircraft. The rotor and blade assembly is rotated by an engine assembly, with the engine assembly, the rotor and blades all positioned on top a multi-directional tilt enabling 10 joint 9. The tubojet is fitted to a multi-directional tilt enabling joint 22 to allow control of lateral movement of the aircraft as well as providing vertical lift and forward propulsion during forward flight.